## Ultrasonic Strain Image Made by Speckle Tracking of B-mode Image

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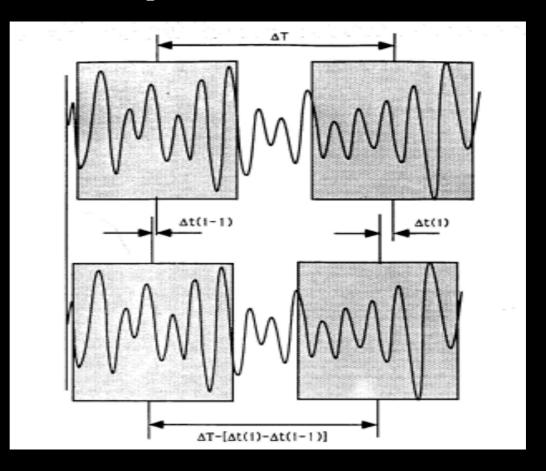
#### Introduction

- Elasticity imaging can provide a significant adjunct to current diagnostic ultrasonic methods
- Most elasticity imaging is derived by RF data and few by envelope data.
- RF data elasticity imaging is more sensitive;
   envelope data is less noisy under larger strain

## Strain estimation by RF data

#### Cross correlation of consequent A-line

$$s(i) = \frac{\Delta t(i) - \Delta t(i-1)}{\Delta T}$$



#### Strain estimation by envelope data

--Speckle tracking of B-mode image

- 1D-cross correlation of consequent column of pixels (like A-line of RF data)(Ophir): lateral displacement is hard to detect.

 2D-Block matching algorithm (Levinston, 1994; Yeung, 1997), time costing full search and multi-level methods

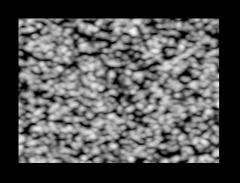
## Goal of this project

- studying the differences of 1D and 2D methods
- studying the differences of full search and multilevel speckle tracking method
- searching other possible strain estimator

#### Materials and Methods

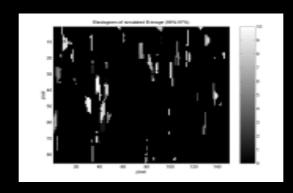
- Target: B-mode images
  - simulated data set
  - breast phantom
  - clinical breast tumor
- Method: 1D and 2D speckle tracking

#### Comparison of Elastogram1 (1D and 2 D)

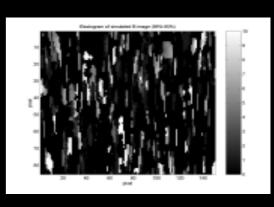


1D

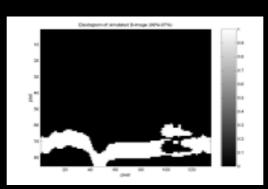
2D

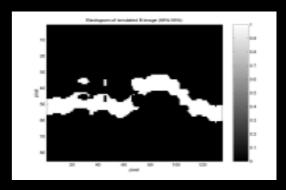


99-97%



99-95%

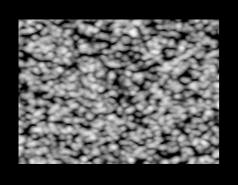




99-97%

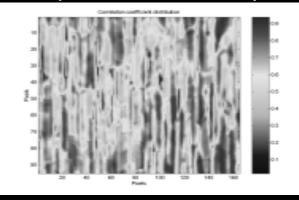
99-95%

 Comparison of correlation coefficients distribution (1D and 2D)

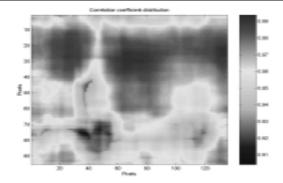


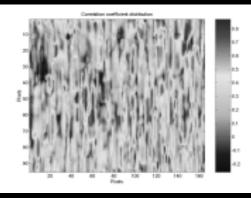
1D

2D

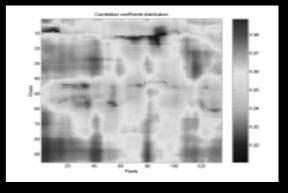


99-97%





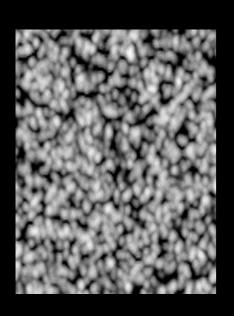
99-95%

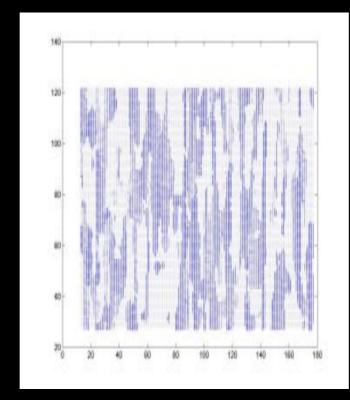


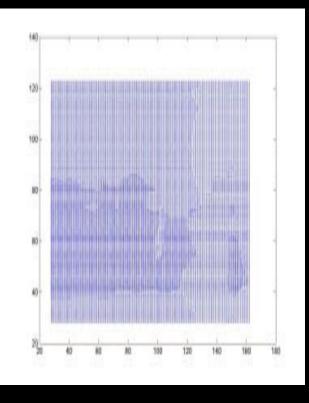
99-97%

99-95%

Comparison of arrow direction distribution
 (1D and 2 D) 1D 2D

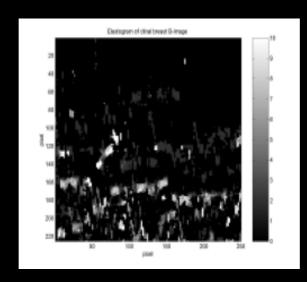


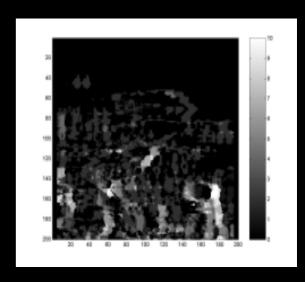




99-95% 99-95%







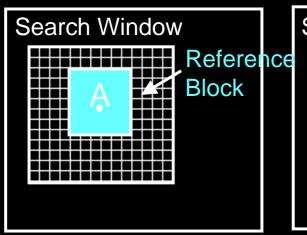
1D 2D

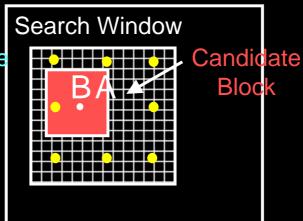
## Improved Speckle Tracking - Multi-level

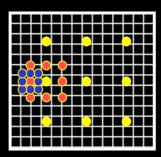
Multiple levels, 9 points estimation in each level

Image Before In-plane Motion

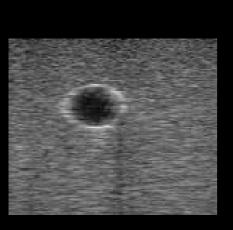
Image After In-plane Motion

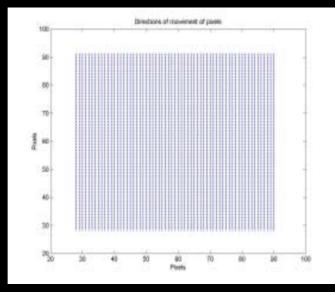


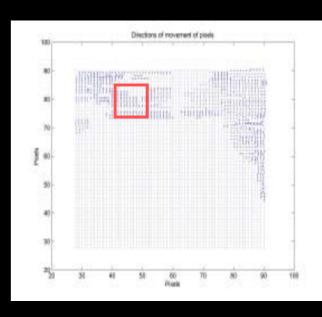




 Comparison of full search and mult-level speckle tracking method

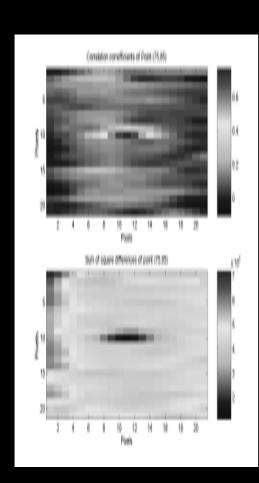






Full search

Two level

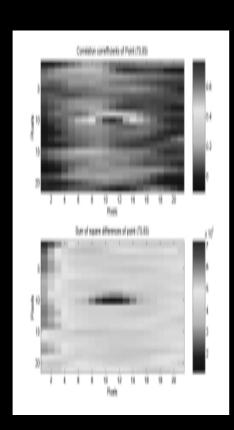


#### D1

475311	427026	456354	ĵ
Mexicon (1873)	(111365)	W. C.	
479950	421806	423350	
500169	405354	405057	1

#### C1

0.1438	0.1397	0.0552
G2 - 1071-2747-207	(0.7736)	9445 0.05000
0.1021	0.1378	0.0935
0.0486	0.1856	0.1605



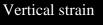
D2			
451723	426930	457179	
451620	(111516) 427890	424554	
482545	413751	411719	1
C2			
0.1463	0.1166	0.0326	
0.1353	(0.7655) 0.0969	0.0751	
0.0804	0.1434	0.1265	

 Comparison of full search method of sum of difference and correlation coefficient

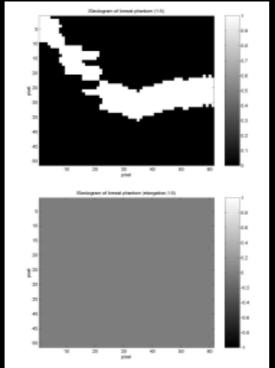
Sum of difference (1-5)

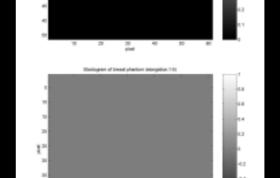
Correlation coefficient

Dissingram of Smoot pharton (1-0)

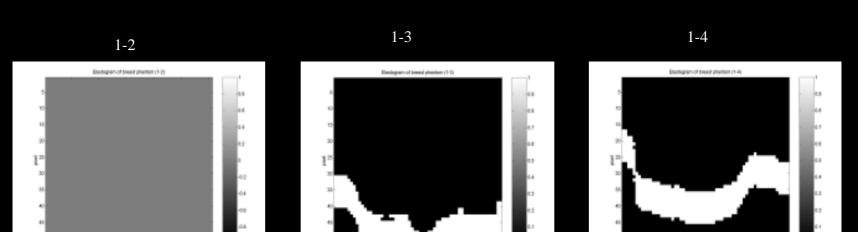


Elongation



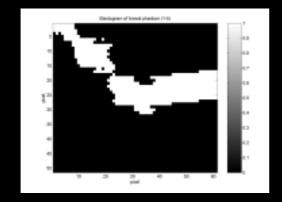


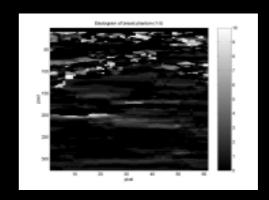
	Sum of differe	Sum of differences		efficients
	Minimal cc	Mean cc	Minimal cc	Mean cc
1-2	0.7387	0.8962	0.7387	0.8962
1-4	0.3944	0.7810	0.3944	0.7810
1-5	0.3520	0.7677	0.3520	0.7679



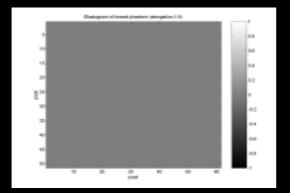
#### Interpolation (1pixel --> 5 pixels)

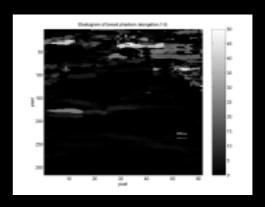
Vertical strain





Elongation

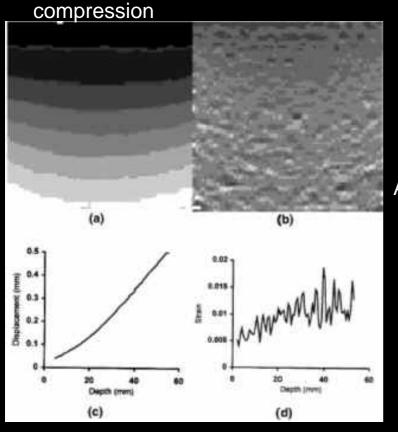


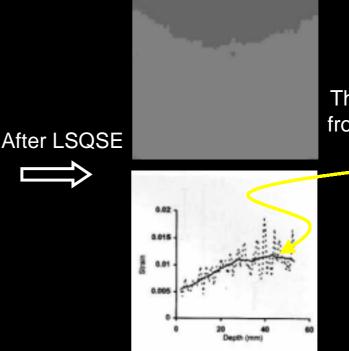


## LSQSE(Least Square Strain **Estimator**)

Homogeneous Strain Image obtained by gel phantom From 1% applied of the displacement field

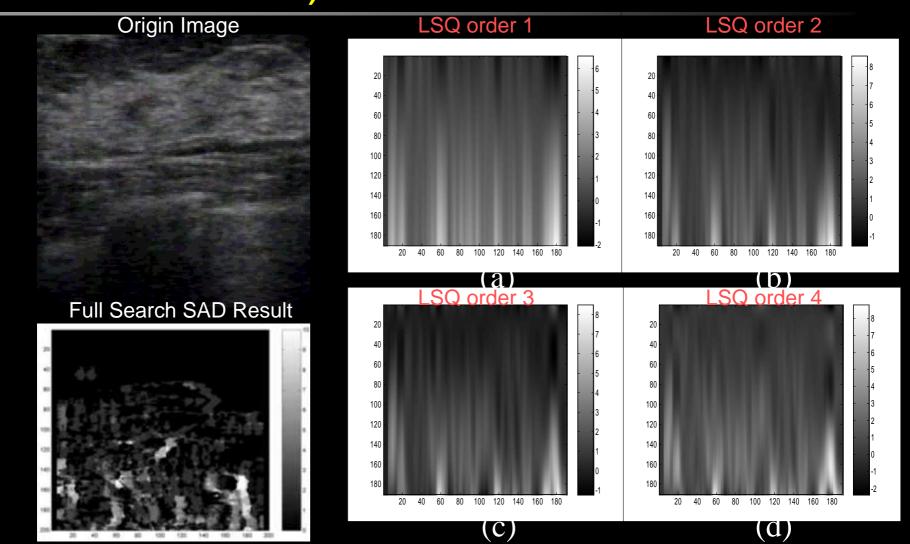
taking the gradient





The middle column from the LSQ strain image

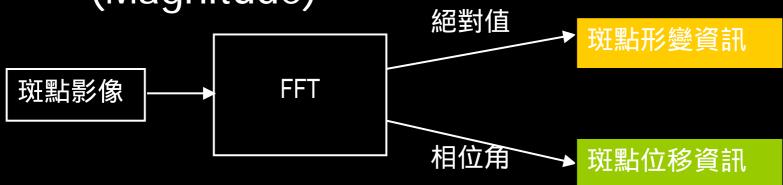
# LSQSE(Least Square Strain Estimator)



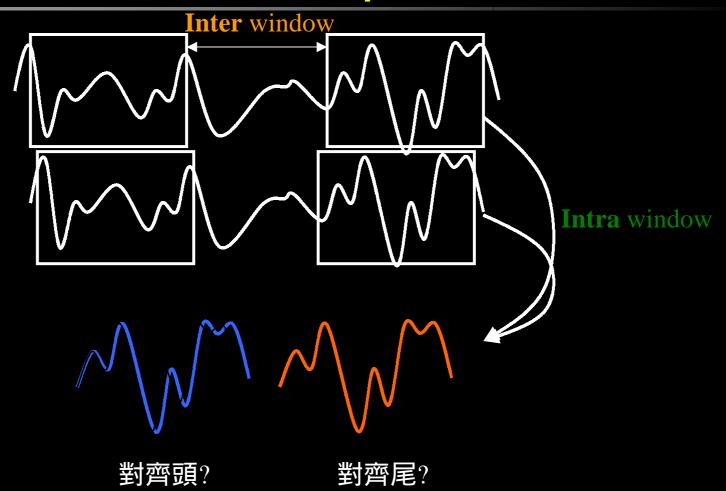
- 報告內容:
  - 原理說明—FFT之特性及優點
  - 文獻參考—Temporal Stretch Method
  - ■方法與步驟
  - ■結果與討論

## 原理說明—FFT之特性及優點

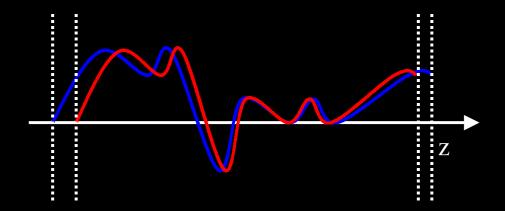
- FFT為快速演算法
- 具有 translation invariant特性 (Magnitude)



## 文獻參考—Temporal Stretch

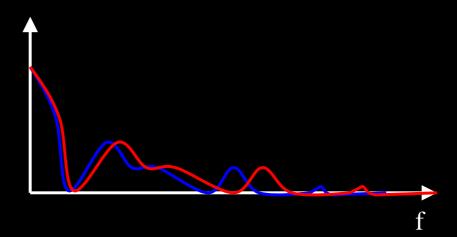


- 由頻域對B-mode影像進行分析
  - Z軸方向的一段組織反射信號

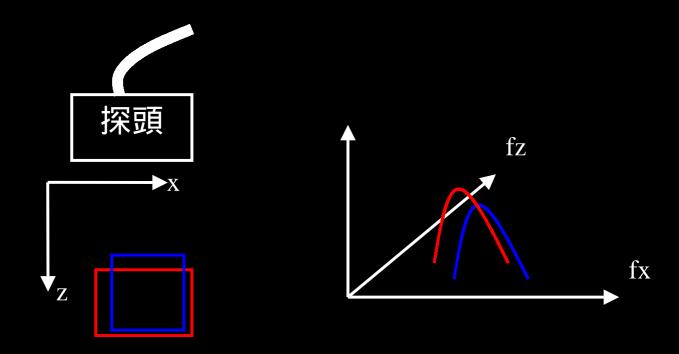


■ 信號與系統理論 :

```
\begin{array}{ccc} \bullet & a(z) & \rightarrow & A( ) \\ a(kz) & \rightarrow & A( /k) \end{array}
```

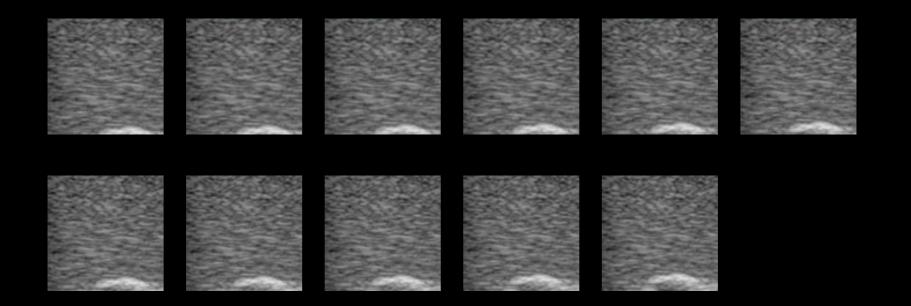


■ 將此方法推廣至二維 :



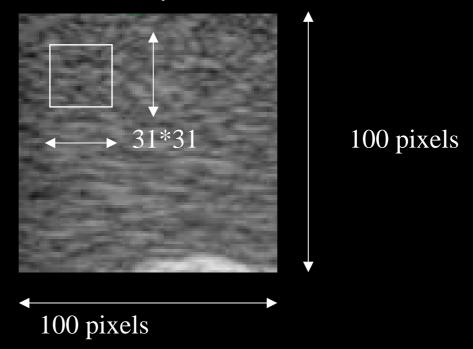
## 方法步驟——形變分析

■ 使用一系列以photoshop進行縮放調整之 speckle影像進行模擬

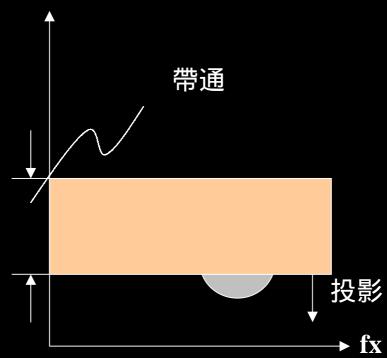


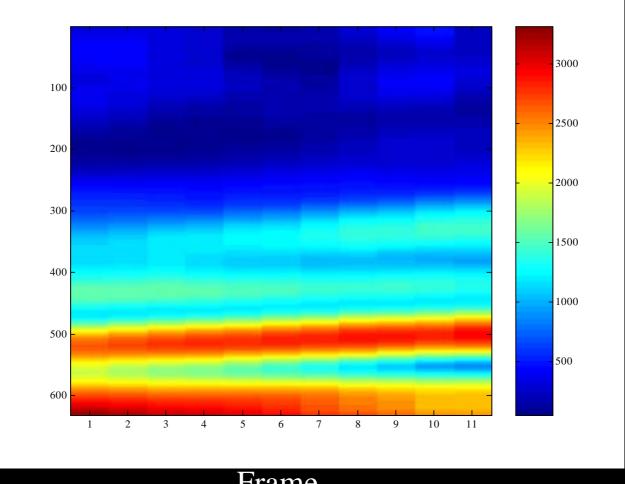
## 方法步驟——形變分析

■ 將每張影像取出31\*31 pixels部分進行 分析(不包含亮點)



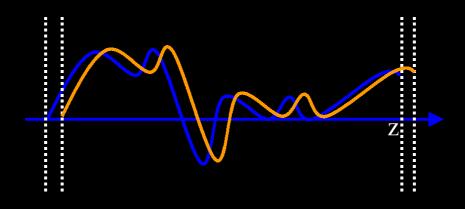
## 方法步驟——形變分析



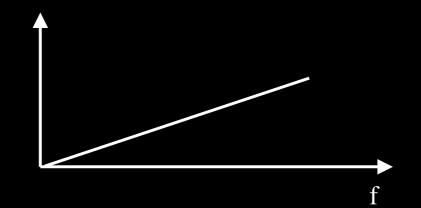


Frame

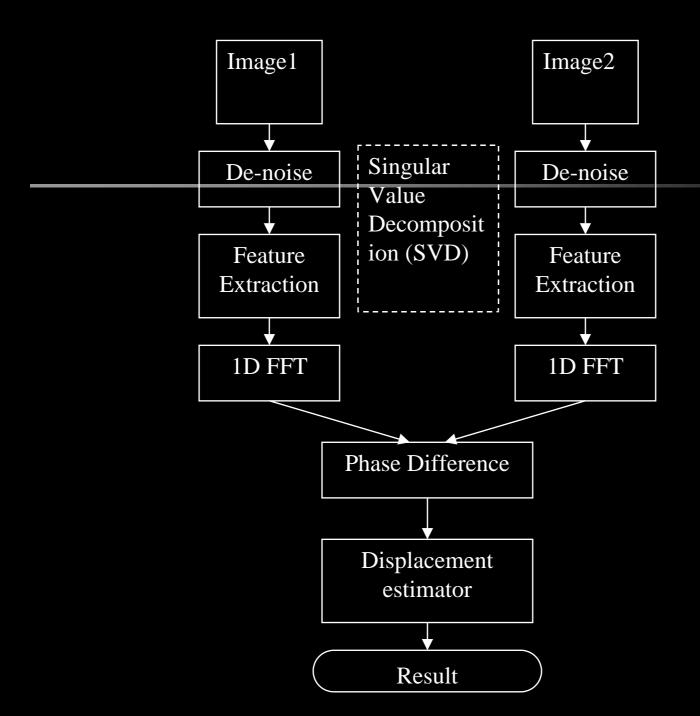
## 方法步驟—位移分析

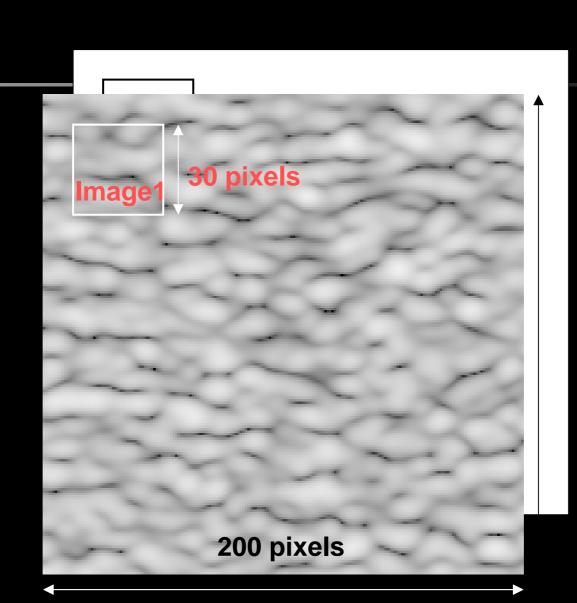


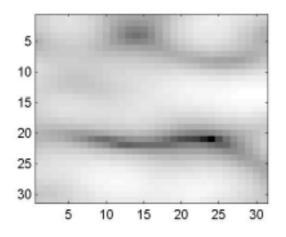
Phase difference

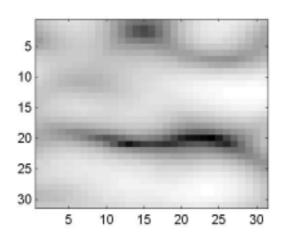


/f = 2 \* Z

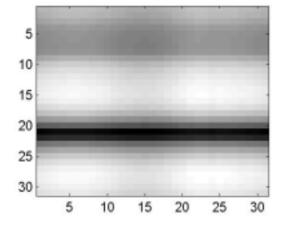


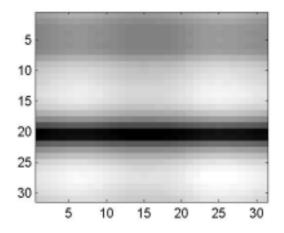


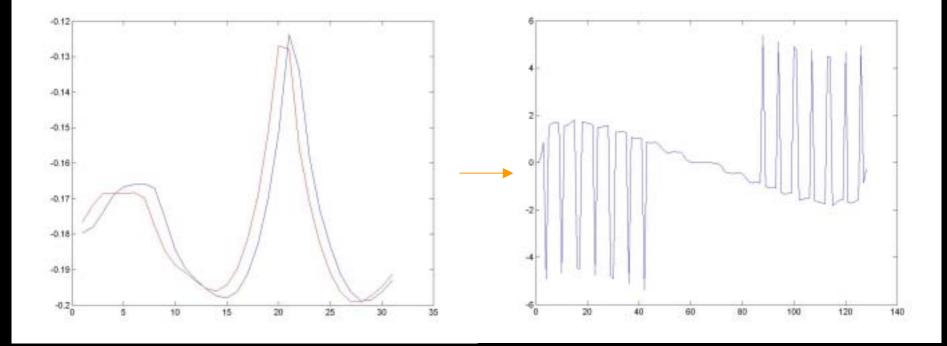


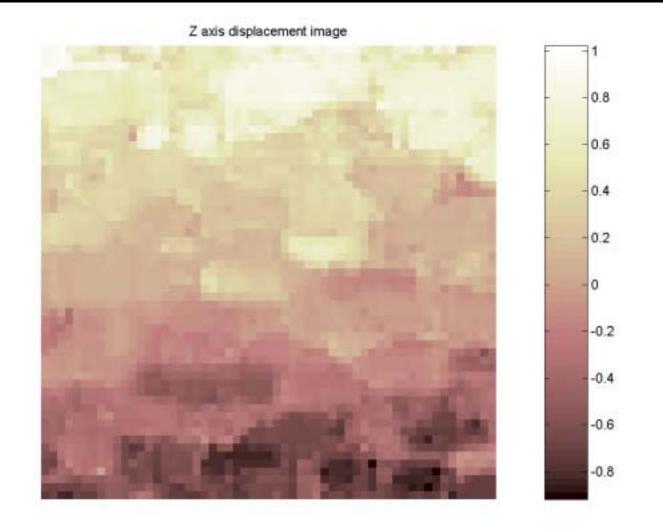


SVD 1'st eigen image



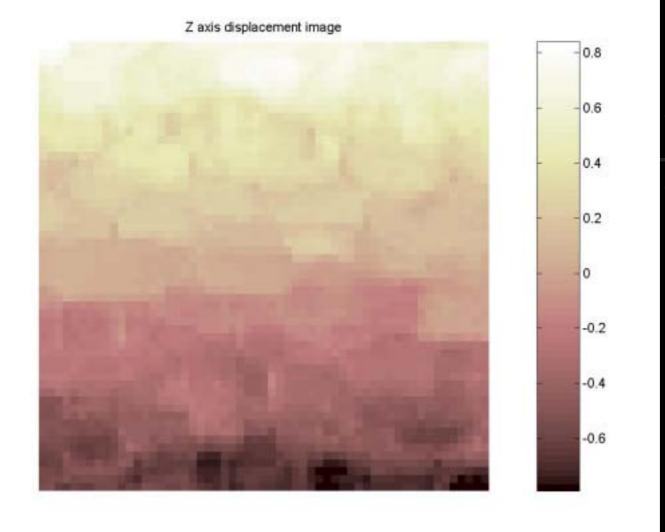




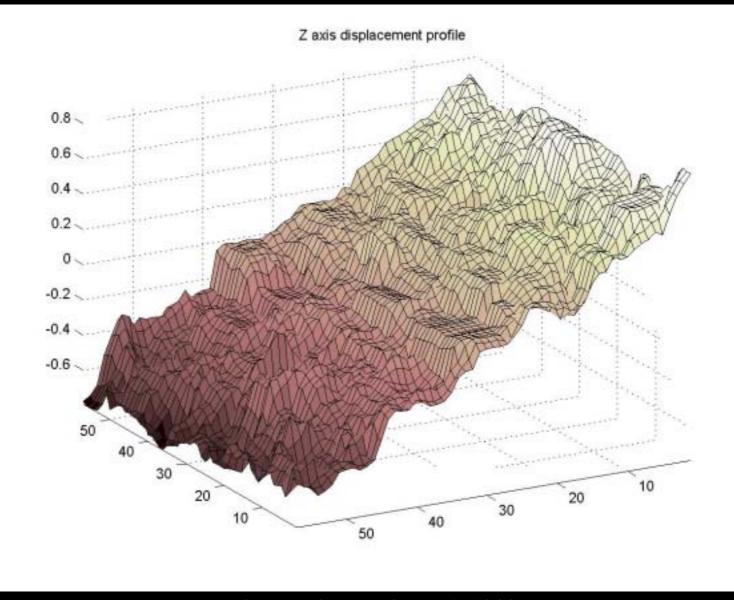


以兩張相鄰strain~=1%之影像計算所得結果。

位移量 向下為正 單位 pixel



以十一張相鄰strain~=1%之影像計算所得結果。 (十張displacement影像複合之結果) → 位移量 向下為正 單位 pixel 位移量 向下為正 單位 pixel



同上一結果(十一張相鄰像計算所得)。 以profile表示,可以看出其線性程度。

## 討論

- ■壓縮1%的200\*200模擬影像,確實可以偵測出 ±1pixel漸層變化的位移量。
- spatial domain的filter、constrain都 尚未派上用場。
- strain是位移量的微分。
- 如果有簡便之類似運算可代替SVD,將比傳統speckle tracking大幅節省運算量。

#### Discussion

- 1D method has higher sensitivity, but also higher noise (lower correlation coefficients).
- More diffuse distribution of strain signal than 2D method
- 2D method has higher precision rate (high correlation coefficients) and best X direction displacement estimate.
- Band like strain signals were estimated for simulation and phantom images, the cause may be due to quantitative error (accumulated of tiny strain relived at the similar row)

#### Discussion

- For clinical breast tumor images, 1D and 2D method could detect the strain both.
- Multiple level speckle tracking method would produce obvious error and is not suitable for ultrasonic strain estimation.
- Full search sum of difference method has near similar high precision rate as the correlation coefficients method
- Interpolation could increase the sensitivity but also the noise, long time period was used in calculation.

#### Future work

- Try the least square strain estimator proposed by Ophir group for smoothing the images(denoise?) in 1D (1 method?)
- Applying pyramid method for fasting the calculating speed of sum of difference method.
- Improving the interpolation method for reducing the noise.

#### References

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